

## Unique Integrable Solution For The Coupled System Of Hammerstein Integral Equations

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### Abstract

We are concerned here with the coupled system of Hammerstein integral equations. The existence of a unique integrable solution will be proved under the lipschitz condition. Also, the monotonicity solution for the coupled system is provided.

### المستخلص

يهتم البحث بالنظام المزدوج لمعادلات هامرشتين التكاملية، حيث يتم إثبات وجود حل تكاملي وحيد تحت شرط لبشز، وعرض اضطرادية الحل لهذا النظام المزدوج أيضا.

Keywords: Integration; Hammerstein; coupled system; lipschitz condition.

### Introduction and Preliminaries

The most frequently investigated for Hammerstein nonlinear integral equation [1][3]:

$$x(t) = \varphi(t) + \int_0^1 k(t,s)f(s,x(s)) ds \quad , \quad t \in [0,1]$$

Here, we prove the existence of a unique integrable solution for the coupled system of Hammerstein integral equations.

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$$\begin{aligned} x(t) &= g_1(t) + \int_0^1 k_1(t,s)f_1(s,y(s)) ds \\ y(t) &= g_2(t) + \int_0^1 k_2(t,s)f_2(s,x(s)) ds \end{aligned} \quad (1) \quad t \in [0,1]$$

Which is proved by applying Banach fixed point principle for Contraction Theorem when the two functions  $f_1$  and  $f_2$  satisfy the lipschitz condition:

$$\|f_i(t,x) - f_i(t,y)\|_{L_1} < c_i \|x - y\|_{L_1}$$

Under certain monotonicity condition by using the technique of measure of noncompactness.

Here, we relax the monotonicity and prove the existence of  $L_1$  – solution of the coupled system of Hammerstein integral equations (1).

Let  $L_1 = L_1(I)$  be the class of Lebesgue integrable functions on  $I = [0; 1]$  with the standard norm:

$$\|x\| = \int_0^1 |x(t)| dt$$

Let  $L_1^* = L_1^*(I)$  be the class of all column vectors of integrable functions [2]:

$$\begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix}, x_i \in L_1, i = 1,2, \text{ and } \|x\|_{L_1} = \sum_{i=1}^2 \|x_i\|_{L_1} = \sum_{i=1}^2 \int_0^1 |x_i(t)| dt$$

**Theorem (1.1) Banach Contraction Mapping Principle**[4]:

Let  $(X, \rho)$  be a complete metric space and let  $T : X \rightarrow X$  be a contraction map. Then  $T$  has a unique fixed point in  $X$ . Moreover, for any  $x_0 \in X$  the sequence  $\{T^n(x_0)\}_{n=0}^{\infty}$  converges to the fixed point.

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**Theorem 1.2:** [5]

Let  $K : I \times I \rightarrow R_+$  be measurable with respect to both variables and such that the integral operator  $K$  generated by  $k$  maps  $L_1$  into itself. If for every  $p \in (0,1)$  and for all  $t_1, t_2 \in I$  the implication:

$$t_1 \leq t_2 \Rightarrow \int_0^p k(t_1, s) ds \leq \int_0^p k(t_2, s) ds$$

holds, then the operator  $K$  transforms the set of positive and nondecreasing functions from  $L_1$  into itself.

### Existing Unique Integrable Solution

Consider the following assumptions:

- (i)  $g_i : I \rightarrow R$  are integrable on  $I$ ;
- (ii)  $f_i : I \times R \rightarrow R$  are measurable in  $t \in I$  for any  $x \in R$  and lipschitz in  $x \in D \subset R$  for any  $t \in I$

**i.e.**  $\|f_i(t, x) - f_i(t, y)\|_{L_1} < c_i \|x - y\|_{L_1}$  and  $|f_i(t, 0)| \leq |a_i(t)|$  ,  $a_i(t) \in L_1$  ;

- (iii)  $k_i : I \times I \rightarrow R$  are integrable in  $t$  for any  $s \in I$  and measurable in  $s$  for any  $t \in I$  such that:

$$\int_0^1 |k_i(t, s)| ds < M_i \quad \text{where } i = 1, 2$$

Consider the operator  $T$  defined by:

$$TW = T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} g_1(t) + \int_0^1 k_1(t, s) f_1(s, y(s)) ds \\ g_2(t) + \int_0^1 k_2(t, s) f_2(s, x(s)) ds \end{pmatrix}$$

**Lemma 2.1 :**

The operator  $T$  maps the space  $L_1^*$  into itself  $T : L_1^* \rightarrow L_1^*$

**Proof:** From the assumption (ii) we have:

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$$\|f_i(t, x) - f_i(t, y)\|_{L_1} < c_i \|x - y\|_{L_1}$$

and  $|f_i(t, 0)| \leq |a_i(t)|$  ,  $a_i(t) \in L_1 \Rightarrow$

$$\|f_i(t, x)\|_{L_1} - \|a_i(t)\|_{L_1} \leq \|f_i(t, x) - f_i(t, 0)\|_{L_1} < c_i \|x\|_{L_1}$$

i.e.  $\|f_i(t, x)\|_{L_1} - \|a_i(t)\|_{L_1} < c_i \|x\|_{L_1}$

Therefore,

$$\|f_i(t, x)\|_{L_1} \leq \|a_i\|_{L_1} + c_i \|x\|_{L_1} \quad (2)$$

**Now,** Let  $\begin{pmatrix} x \\ y \end{pmatrix} \in L_1^*$ :

$$T \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} g_1(t) + \int_0^1 k_1(t, s) f_1(s, y(s)) ds \\ g_2(t) + \int_0^1 k_2(t, s) f_2(s, x(s)) ds \end{pmatrix}$$

$$\begin{aligned} \|T \begin{pmatrix} x \\ y \end{pmatrix}\|_{L_1}^* &= \left\| g_1(t) + \int_0^1 k_1(t, s) f_1(s, y(s)) ds \right\|_{L_1} \\ &+ \left\| g_2(t) + \int_0^1 k_2(t, s) f_2(s, x(s)) ds \right\|_{L_1} \\ &= \int_0^1 |g_1(t) + \int_0^1 k_1(t, s) f_1(s, y(s))| ds dt \\ &+ \int_0^1 |g_2(t) + \int_0^1 k_2(t, s) f_2(s, x(s))| ds dt \\ &\leq \int_0^1 |g_1(t)| dt + \int_0^1 \int_0^1 |k_1(t, s)| |f_1(s, y(s))| ds dt \\ &+ \int_0^1 |g_2(t)| dt + \int_0^1 \int_0^1 |k_2(t, s)| |f_2(s, x(s))| ds dt \end{aligned}$$

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Interchange the order of integration we get:

$$\begin{aligned}
 \|T \begin{pmatrix} x \\ y \end{pmatrix}\|_{L_1}^* &\leq \|g_1\|_{L_1} + \|g_2\|_{L_1} + \int_0^1 |f_1(s, y(s))| \left( \int_0^1 |k_1(t, s)| dt \right) ds \\
 &\quad + \int_0^1 |f_2(s, x(s))| \left( \int_0^1 |k_2(t, s)| dt \right) ds \\
 &\leq \|g_1\|_{L_1} + \|g_2\|_{L_1} + M_1 \int_0^1 |f_1(s, y(s))| ds + M_2 \int_0^1 |f_2(s, x(s))| ds \\
 &\leq \|g_1\|_{L_1} + \|g_2\|_{L_1} + M_1 \|f_1(s, y)\|_{L_1} + M_2 \|f_2(s, x)\|_{L_1}
 \end{aligned}$$

By inequality (2)

$$\begin{aligned}
 \|T \begin{pmatrix} x \\ y \end{pmatrix}\|_{L_1}^* &\leq \|g_1\|_{L_1} + \|g_2\|_{L_1} + M_1 \|a_1\|_{L_1} + M_1 C_1 \|y\|_{L_1} \\
 &\quad + M_2 \|a_2\|_{L_1} + M_2 C_2 \|x\|_{L_1} \\
 &= \left[ \|g_1\|_{L_1} + \|g_2\|_{L_1} \right] + M \left[ \|a_1\|_{L_1} + \|a_2\|_{L_1} \right] \\
 &\quad + MC \left[ \|x\|_{L_1} + \|y\|_{L_1} \right]
 \end{aligned}$$

Where,  $M = \max\{M_1, M_2\}$  and,  $MC = \max\{M_1 C_1, M_2 C_2\}$

Thus,

$$\|T \begin{pmatrix} x \\ y \end{pmatrix}\|_{L_1}^* \leq \left\| \begin{pmatrix} g_1 \\ g_2 \end{pmatrix} \right\|_{L_1}^* + M \left\| \begin{pmatrix} a_1 \\ a_2 \end{pmatrix} \right\|_{L_1}^* + MC \left\| \begin{pmatrix} x \\ y \end{pmatrix} \right\|_{L_1}^*$$

Therefore,

$$\|TW\|_{L_1}^* \leq \|G\|_{L_1}^* + M\|A\|_{L_1}^* + CM\|W\|_{L_1}^*$$

The last estimate shows that the operator  $T$  maps the space  $L_1^*$  into itself.

**Theorem 2.2:**

Let the assumptions (i) – (iii) be satisfied then the coupled system (1) has a unique integrable solution in  $\begin{pmatrix} x \\ y \end{pmatrix} \in L_1^*$

**Proof:**

$$U = \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} = \begin{pmatrix} g_1(t) + \int_0^1 k_1(t,s)f_1(s,y_1(s)) \, ds \\ g_2(t) + \int_0^1 k_2(t,s)f_2(s,x_1(s)) \, ds \end{pmatrix}$$

$$V = \begin{pmatrix} x_2 \\ y_2 \end{pmatrix} = \begin{pmatrix} g_1(t) + \int_0^1 k_1(t,s)f_1(s,y_2(s)) \, ds \\ g_2(t) + \int_0^1 k_2(t,s)f_2(s,x_2(s)) \, ds \end{pmatrix}$$

Let,

$$TU = \begin{pmatrix} g_1(t) + \int_0^1 k_1(t,s)f_1(s,y_1(s)) \, ds \\ g_2(t) + \int_0^1 k_2(t,s)f_2(s,x_1(s)) \, ds \end{pmatrix}$$

Indeed,  $T : L_1^* \rightarrow L_1^*$

$$TU - TV = \begin{pmatrix} \int_0^1 k_1(t,s) [f_1(s,y_1(s)) - f_1(s,y_2(s))] \, ds \\ \int_0^1 k_2(t,s) [f_2(s,x_1(s)) - f_2(s,x_2(s))] \, ds \end{pmatrix}$$

$$\begin{aligned} \|TU - TV\|_{L_1^*}^* &= \left\| \int_0^1 k_1(t,s) [f_1(s,y_1(s)) - f_1(s,y_2(s))] \, ds \right\| \\ &\quad + \left\| \int_0^1 k_2(t,s) [f_2(s,x_1(s)) - f_2(s,x_2(s))] \, ds \right\| \\ \|TU - TV\|_{L_1^*}^* &= \int_0^1 |TU - TV| dt \end{aligned}$$

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$$\begin{aligned}
 \|TU - TV\|_{L_1}^* &\leq \int_0^1 \left| \int_0^1 k_1(t, s) [f_1(s, y_1(s)) - f_1(s, y_2(s))] \right| ds \\
 &\quad + \int_0^1 \left| \int_0^1 k_2(t, s) [f_2(s, x_1(s)) - f_2(s, x_2(s))] \right| ds \\
 &\leq \int_0^1 \int_0^1 |k_1(t, s)| |f_1(s, y_1(s)) - f_1(s, y_2(s))| ds \\
 &\quad + \int_0^1 \int_0^1 |k_2(t, s)| |f_2(s, x_1(s)) - f_2(s, x_2(s))| ds
 \end{aligned}$$

Interchange the order of integration we get:

$$\begin{aligned}
 \|TU - TV\|_{L_1}^* &\leq \int_0^1 |f_1(s, y_1(s)) - f_1(s, y_2(s))| \left[ \int_0^1 |k_1(t, s)| dt \right] ds \\
 &\quad + \int_0^1 |f_2(s, x_1(s)) - f_2(s, x_2(s))| \left[ \int_0^1 |k_2(t, s)| dt \right] ds \\
 &\leq M_1 \int_0^1 |f_1(s, y_1(s)) - f_1(s, y_2(s))| ds \\
 &\quad + M_2 \int_0^1 |f_2(s, x_1(s)) - f_2(s, x_2(s))| ds \\
 &\leq M_1 \|f_1(s, y_1(s)) - f_1(s, y_2(s))\|_{L_1} \\
 &\quad + M_2 \|f_2(s, x_1(s)) - f_2(s, x_2(s))\|_{L_1} \\
 &\leq M_1 C_1 \|y_1 - y_2\|_{L_1} + M_2 C_2 \|x_1 - x_2\|_{L_1} \\
 &\leq MC \left( \|y_1 - y_2\|_{L_1} + \|x_1 - x_2\|_{L_1} \right) \\
 \|TU - TV\|_{L_1}^* &\leq MC \|U - V\|_{L_1}
 \end{aligned}$$

Where  $MC = \max \{ M_1 C_1, M_2 C_2 \}$

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Then,

If  $MC < 1$  then  $T$  is a contraction.

By using fixed point Theorem,  $\exists x, y \in L_1$  such that  $TU = U$ .

### Existing Monotonic Integrable Solution

#### Corollary 3.1 :

Let the assumptions of Theorem(2.2) be satisfied if  $k_1$  and  $g_1$  are monotonic in  $t$ , then  $x$  is monotonic solution in  $I$  and if  $k_2$  and  $g_2$  are monotonic in  $t$ , then  $y$  is monotonic solution in  $I$ .

#### Proof:

let  $t_2 > t_1$ ,  $t_1, t_2 \in I$ , then:

$$\begin{aligned} (1) \quad x(t) &= g_1(t) + \int_0^1 k_1(t,s) f_1( s, y(\varphi_1(s)) ) ds \\ x(t_2) &= g_1(t_2) + \int_0^1 k_1(t_2,s) f_1( s, y(\varphi_1(s)) ) ds \\ &\geq g_1(t_1) + \int_0^1 k_1(t_1,s) f_1( s, y(\varphi_1(s)) ) ds \\ &= x(t_1) \end{aligned}$$

Then,  $x(t)$  is monotonical nondecreasing.

Also,

$$\begin{aligned} (2) \quad y(t) &= g_2(t) + \int_0^1 k_2(t,s) f_2( s, y(\varphi_2(s)) ) ds \\ y(t_2) &= g_2(t_2) + \int_0^1 k_2(t_2,s) f_2( s, y(\varphi_2(s)) ) ds \end{aligned}$$



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$$\begin{aligned} &\geq g_2(t_1) + \int_0^1 k_2(t_1, s) f_2( s, y(\varphi_2(s)) ) ds \\ &= y(t_1) \end{aligned}$$

Then,  $y(t)$  is monotonical nondecreasing .

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